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ON CONTINUITY OF A $(3,1,\rho)$ – METRIC

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Abstract. A given $(3,1,\rho)$ – metric d on a set M, induces more than one topology τ on M. In general the map d from the third power of (M,τ) to the real numbers with the usual topology is not continuous. In this paper we consider one of the topologies τ on M and some additional conditions that will imply the continuity of d.

1. Introduction

The geometric properties, their axiomatic classification and the generalization of metric spaces have been considered in a lot of papers. We will mention some of them: K. Menger ([11]), V. Nemytzki, P.S. Aleksandrov ([13], [1]), Z. Mamuzic ([10]), S. Gähler ([8]), A. V. Arhangelskii, M. Choban, S. Nedev ([2], [3], [14]), R. Kopperman ([9]), J. Usan ([15]), B. C. Dhage, Z. Mustafa, B. Sims ([5], [12]). The notion of (n,m,ρ) – metric is introduced in [6]. Connections between some of the topologies induced by a $(3,1,\rho)$ – metric d and topologies induced by a pseudo-o-metric, o-metric and symmetric are given in [7]. For a given $(3,1,\rho)$ – metric d on set M, $j \in \{1,2\}$, seven topologies $\pi(G,d)$, $\pi(H,d)$, $\pi(D,d)$, $\pi(N,d)$, $\pi(W,d)$, $\pi(S,d)$ and $\pi(K,d)$ on M, induced by d, are defined in [4], and several properties of these topologies are shown.

In this paper we consider only the topology (G,d) induced by a $(3,1,\rho)$ – metric d. For $\tau = \tau(G,d)$, we will state two conditions for d and show that these conditions imply the continuity of d, as a map from the third power of the topological space (M,τ) to the real numbers with the usual topology.

We recall the basic notions.

Let *M* be a nonempty set, and let $d:M^3 \to R_0^+ = [0,\infty)$. We state three conditions for such a map.

- (*M*0) d(x, x, x) = 0, for any $x \in M$;
- (P) d(x, y, z) = d(x, z, y) = d(y, x, z) for any $x, y, z \in M$; and
- (M1) d(x, y, z)d(x, y, a) + d(x, a, z) + d(a, y, z), for any $x, y, z, a \in M$.

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For a map d as above let $\rho = \{(x,y,z) \mid (x,y,z) \in M^3, d(x,y,z) = 0\}$. The set ρ is a (3,1)-equivalence on M, as defined and discussed in [6], [4]. The sets $\Delta = \{(x,x,x) \mid x \in M\}$ and $\nabla = \{(x,x,y) \mid x,y \in M\}$ are (3,1)-equivalences on M. The condition (M0) implies that $\Delta \subseteq \rho$.

Definition 1. Let $d: M^3 \to R_0^+$ and ρ be as above. If d satisfies (M0), (P) and (M1) we say that d is a $(3,1,\rho)$ – metric on M.

Let d be a $(3,1,\rho)$ – metric on M, $x,y \in M$ and $\varepsilon > 0$. As in [4], we consider the following ε – ball, as subset of M:

 $B(x, y, \varepsilon) = \{z \mid z \in M, d(x, y, z) < \varepsilon\} - \varepsilon$ -ball with center at (x, y) and radius ε .

Among the others, a $(3,1,\rho)$ – metric d on M induces the topology $\tau(G,d)$ -generated by all the ε -balls $B(x,y,\varepsilon)$, i.e. the topology whose base is the set of the finite intersections of ε -balls $B(x,y,\varepsilon)$, (see as [4]).

2. CONTINUITY OF A $(3,1,\rho)$ – METRIC d FOR $\tau(G,d)$

Proposition 1. Let d be a $(3,1,\rho)$ – metric on M, let $\tau = \tau(G,d)$, and let d satisfies the following two conditions:

(A) For each x_1, x_2, x_3 of M there is permutation i_1, i_2, i_3 of 1,2,3 such that

$$d(x_{i_1}, x_{i_1}, x_{i_2}) = d(x_{i_1}, x_{i_1}, x_{i_3}) = d(x_{i_2}, x_{i_3}, x_{i_3}) = 0$$
 and

(B) For each two points u, v of M and each $\varepsilon > 0$ there are open sets $U_u, U_v \in \tau$ such that $u \in U_u$, $v \in U_v$ and for each $x \in U_u$ and $y \in U_v$:

$$d(u, x, y) < \varepsilon$$
 and $d(v, x, y) < \varepsilon$.

Then, the $(3,1,\rho)$ – metric d is a continuous function.

Proof. Let u, v, t be points of M and $\varepsilon > 0$. Using (A), w.l.o.g. we can set $x_1 = u$, $x_2 = t$ and $x_3 = v$. Thus:

$$d(u,u,t) = d(u,u,v) = d(t,v,v) = 0.$$
(1)

For u, v of M and $\varepsilon > 0$, the condition (B) implies that there are open neighborhoods U_u, U_v of u and v, such that for each x of U_u and each y of U_v we have

$$d(x, y, u) < \varepsilon/6$$
 and $d(x, y, v) < \varepsilon/6$. (2)

Let U_u^1 and U_v^1 be the open sets defined by:

$$U_u^1 = B(u, v, \varepsilon/6) \cap B(u, t, \varepsilon/6) \cap U_u \text{ and } U_v^1 = B(t, v, \varepsilon/6) \cap U_v.$$
 (3)

Then, (1) implies that $u \in U_u^1$ and $v \in U_v^1$. This together with (3), implies that for each x of U_u^1 and each y of U_v^1 , we have

$$d(u,v,x) < \varepsilon / 6d(u,t,x) < \varepsilon / 6$$
 and $d(t,v,y) < \varepsilon / 6$. (4)

For u,t of M and $\varepsilon > 0$, the condition (B) implies that there are open neighborhoods U_u^2 of u and U_t of t such that for each x of U_u^2 and each z of U_t we have

$$d(u,x,z) < \varepsilon/6$$
 and $d(t,x,z) < \varepsilon/6$. (5)

For t, v of M and $\varepsilon > 0$, the condition (B) implies that there are open neighborhoods U_t^1 of t and U_v^2 of v such that for each z of U_t^1 and each y of U_v^2 we have

$$d(t,z,y) < \varepsilon/6$$
 and $d(v,z,y) < \varepsilon/6$. (6)

Let $U_u^{'} = U_u \cap U_u^1 \cap U_u^2$, $U_v^{'} = U_v \cap U_v^1 \cap U_v^2$ and $U_t^{'} = U_t \cap U_t^1$. The construction of these open sets implies that $u \in U_u^{'}$, $v \in U_v^{'}$ and $t \in U_t^{'}$. Moreover, for each x of $U_u^{'}$, y of $U_v^{'}$ and z of $U_t^{'}$, using (2), (4), (5) and (6), and the tetrahedral inequality (M1) several times we obtain the following inequalities:

$$d(u,t,v) \le d(u,t,x) + d(u,x,v) + d(x,t,v) < \varepsilon/6 + \varepsilon/6 + d(x,t,v)$$

$$\le \varepsilon/3 + d(x,t,y) + d(x,y,v) + d(y,t,v) < \varepsilon/3 + d(x,t,y) + \varepsilon/6 + \varepsilon/6$$

$$\le 2\varepsilon/3 + d(x,t,z) + d(x,z,y) + d(z,t,y) < 2\varepsilon/3 + \varepsilon/6 + d(x,z,y) + \varepsilon/6$$

$$= d(x,z,y) + \varepsilon,$$
(7)

$$d(x,z,y) \le d(x,z,t) + d(x,t,y) + d(t,z,y) < \varepsilon/6 + \varepsilon/6 + d(x,t,y)$$

$$\le \varepsilon/3 + d(x,t,v) + d(x,v,y) + d(v,t,y) < \varepsilon/3 + d(x,t,v) + \varepsilon/6 + \varepsilon/6$$

$$\le 2\varepsilon/3 + d(x,t,u) + d(x,u,v) + d(u,t,v) < 2\varepsilon/3 + \varepsilon/6 + d(u,t,v) + \varepsilon/6$$

$$= d(u,t,v) + \varepsilon.$$
(8)

Next, (7) and (8) imply that:

$$|d(u,t,v)-d(x,z,y)|<\varepsilon$$
.

All this shows that d is a continuous function from M^3 to R with the usual topology.

With the next example we show the existence of a continuous $(3,1,\rho)$ – metric d satisfying the condition (A), but not satisfying the condition (B) as in Proposition 1.

Example 1. Let $M = (p_1) \cup (p_2)$ whereas (p_1) and (p_2) are parallel lines and let $d: M^3 \to R_0^+$ be defined by:

$$d(x, y, z) = \begin{cases} 0, & x = y = z \text{ or } x \neq y \neq z \neq x \text{ and } x, y, z \in (p_k), k = 1, 2 \\ 1, & \text{in other cases} \end{cases}$$

$$d(x, x, y) = \begin{cases} 0, & x, y \in (p_k), k = 1, 2 \text{ or } x \in (p_1), y \in (p_2) \\ 1, & x \in (p_2), y \in (p_1). \end{cases}$$

It is easy to show that d is a $(3,1,\rho)$ – metric on M with

$$\rho = \Delta \cup \{(x, x, y) | x \in (p_1), y \in (p_2) \text{ or } x, y \in (p_k), k = 1, 2\}$$
$$\cup \{(x, y, z) | x \neq y \neq z \neq x \text{ and } x, y, z \in (p_k), k = 1, 2\}.$$

For $x \neq y \in M$ and $\varepsilon > 0$,

$$B(x, y, \varepsilon) = \begin{cases} (p_k), & x \neq y, & x, y \in (p_k), k = 1, 2, \varepsilon \le 1 \\ \{x\}, & x \neq y, & x \in (p_1), y \in (p_2), \varepsilon \le 1 \\ M, & \varepsilon > 1, \end{cases}$$

and for $x = y \in M$ and $\varepsilon > 0$

$$B(x, x, \varepsilon) = \begin{cases} (p_2), & x \in (p_2), \varepsilon \le 1 \\ M, & x \in (p_1), \varepsilon > 1. \end{cases}$$

From this it follows that $\tau = \tau(G, d) = D_{(p_1)} \cup \{(p_2) \cup V | V \subseteq (p_1)\}$ where $D_{(p_1)}$ is the discrete topology on (p_1) .

First we show that the $(3.1, \rho)$ – metric d satisfies the condition (A).

- If $x, y, z \in (p_k), k = 1, 2$, then d(x, x, y) = d(x, x, z) = d(y, z, z) = 0.
- If $x, y \in (p_1)$, $z \in (p_2)$, then d(y, y, z) = d(y, y, z) = d(x, z, z) = 0.
- If $x \in (p_1)$, $y, z \in (p_2)$, then d(x, x, y) = d(x, x, z) = d(y, z, z) = 0.
- If $x = z \in (p_2)$, $y \in (p_1)$, then d(x, x, x) = d(x, y, y) = 0 and d(y, y, y) = d(y, y, x) = 0.

We will show that the $(3,1,\rho)$ – metric d is a continuous function. For each x,y of M we define the map $f_{x,y}:M\to R$ by $f_{x,y}(z)=d(x,y,z)$.

Let U be an open set in R with the usual topology, such that $1 \in U$ and $0 \notin U$. Then

$$f_{x,y}^{-1}(U) = \{z | f_{x,y}(z) \in U\} = \{z | d(x, y, z) = 1\}.$$

We consider the following cases:

- if $x \neq y$ and $x, y \in (p_1)$, then $f_{x,y}^{-1}(U) = (p_2) \in \tau$,
- if $x \neq y$ and $x, y \in (p_2)$, then $f_{x,y}^{-1}(U) = (p_1) \in \tau$,
- if $x \neq y$ and $x \in (p_1)$, $y \in (p_2)$, then $f_{x,y}^{-1}(U) = (p_1) \setminus \{x\} \cup (p_2) \in \tau$,
- if x = y and $x \in (p_1)$, then $f_{x,x}^{-1}(U) = \emptyset \in \tau$,
- if x = y and $x \in (p_2)$, then $f_{x,x}^{-1}(U) = (p_1) \in \tau$.

Let V be an open set in R such that $0 \in V, 1 \notin V$. Then

$$f_{x,y}^{-1}(V) = \{z | f_{x,y}(z) \in V\} = \{z | d(x, y, z) = 0\}.$$

We consider the following cases:

- if if $x \neq y$ and $x, y \in (p_1)$, then $f_{x,y}^{-1}(V) = (p_1) \in \tau$,

- if $x \neq y$ and $x, y \in (p_2)$, then $f_{x,y}^{-1}(V) = (p_2) \in \tau$,
- if $x \neq y$ and $x \in (p_1)$, $y \in (p_2)$, then $f_{x,y}^{-1}(V) = \{x\} \in \tau$,
- if x = y and $x \in (p_1)$, then $f_{x,x}^{-1}(V) = M \in \tau$,
- if x = y and $x \in (p_2)$, then $f_{x,x}^{-1}(V) = (p_2) \in \tau$.

Let W be an open set in R such that $0,1 \in W$. Then

$$f_{x,y}^{-1}(W) = \{z | f_{x,y}(z) \in W\} = \{z | d(x,y,z) = 0 \text{ or } d(x,y,z) = 1\} = M \in \tau.$$

All this implies that d is a continuous function.

Next, we show that d does not satisfy the condition (B) from the above proposition. Let $u,v\in M$, and let $u\in (p_1),\ v\in (p_2)$ and $0<\varepsilon<1$. For each open neighborhoods U_u of u and U_v of v, for x=u and each y=v we have

$$d(u, x, y) = d(u, u, v) = 0 < \varepsilon$$
 and $d(v, x, y) = d(u, v, v) = 1 \nleq \varepsilon$.

Hence, the condition (B) is not satisfied.

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