

GEOMETRICAL INTERPRETATION OF THE ANTISYMMETRIC
 COVARIANT DIFFERENTIATION

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Abstract. In this paper it is given a geometrical interpretation of the differentiation (1), where A is a tensor field of type (r,s) . Indeed it is proved the equality (5) where ϕ^D denotes the parallel displacement along the curve $\tau_4^{-1} \tau_3^{-1} \tau_2^{-1} \tau_1^0$, and $\xi^r = \delta^r_k$, $\eta^s = \delta^s_p$ (fig. 1).

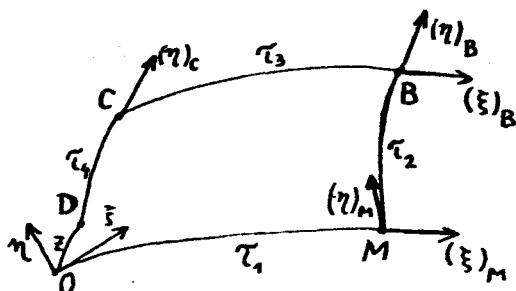


Fig. 1

Let M be an n -dimensional manifold which is endowed with a linear connection. We choose an arbitrary point $O \in M$ and a local coordinate system x^1, \dots, x^n in a neighbourhood of O . We shall denote by C^2 the set of all functions which are twice differentiable and the second derivative is a continuous function in that neighbourhood with respect to the coordinate system (x^i) .

Let $A_{j_1 \dots j_s}^{i_1 \dots i_r} \in C^2$ be the tensor field of type (r,s) , then

$$(DA)_{j_1 \dots j_s k p}^{i_1 \dots i_r} = A_{j_1 \dots j_s ; k p}^{i_1 \dots i_r} - A_{j_1 \dots j_s ; p k}^{i_1 \dots i_r} \quad (1)$$

defines a differentiation which is antisymmetric with respect to the indices k and p . In this paper we will give a geometrical interpretation for this differentiation. Using the Ricci identity, (1) can be written in the following form

$$\begin{aligned}
 \text{(DA)} \quad & \overset{i_1 \dots i_r}{j_1 \dots j_s} k p = -R \overset{i_1}{q k p} A \overset{q i_2 \dots i_r}{j_1 \dots j_s} - \dots - R \overset{i_r}{q k p} A \overset{i_1 \dots q}{j_1 \dots j_s} + \\
 & + R \overset{q}{j_1 k p} A \overset{i_1 \dots i_r}{q j_2 \dots j_s} + \dots + R \overset{q}{j_s k p} A \overset{i_1 \dots i_r}{j_1 \dots q} + T \overset{q}{p k} A \overset{i_1 \dots i_r}{j_1 \dots j_s}; q.
 \end{aligned} \tag{2}$$

Let $\xi, \eta \in T_0(M)$ (fig. 1), and let $\tau_1(t)$ ($0 \leq t \leq \Delta u$), $\tau_2(t)$ ($0 \leq t \leq \Delta v$), $\tau_3(t)$ ($0 \leq t \leq \Delta u$) and $\tau_4(t)$ ($0 \leq t \leq \Delta v$) be geodesic lines which connect O and M, M and B, B and C, C and D respectively, such that

$$\begin{aligned}
 (d\tau_1(t)/dt)_{t=0} &= \xi, & (d\tau_2(t)/dt)_{t=0} &= (\eta)_M, \\
 (d\tau_3(t)/dt)_{t=0} &= -(\xi)_B, & (d\tau_4(t)/dt)_{t=0} &= -(\eta)_C.
 \end{aligned}$$

In the above formulas $(\eta)_M$ is the vector at the point M which is obtained by parallel displacement of η along the curve τ_1 , $(\xi)_B$ is the vector at the point B which is obtained by parallel displacement of ξ along the curve $\tau_1 \cdot \tau_2$, and $(\eta)_C$ is the vector at the point C which is obtained by parallel displacement of η along the curve $\tau_1 \cdot \tau_2 \cdot \tau_3$.

Now we are going to find the differences of the coordinates between the points D and O to the second order of approximation with respect to Δu and Δv . Since τ_1 is a geodesic line, it holds

$$\begin{aligned}
 (x^k)_M - (x^k)_O &= (d\tau_1^k(t)/dt)_{t=0} \Delta u + \frac{1}{2} (d^2\tau_1^k(t)/dt^2)_{t=0} (\Delta u)^2 + \\
 &+ o(\Delta u^2) = \xi^k \Delta u - \frac{1}{2} \Gamma_{rs}^k \xi^r \xi^s (\Delta u)^2 + o(\Delta u^2).
 \end{aligned}$$

Similarly we can calculate the differences $(x^k)_B - (x^k)_M$, $(x^k)_C - (x^k)_B$ and $(x^k)_D - (x^k)_C$, and one can obtain that

$$(x^k)_D - (x^k)_O = T_{rs}^k \xi^r \eta^s \Delta u \Delta v + o(\Delta u^2) + o(\Delta v^2). \tag{3}$$

Specially, if $\xi^r = \delta_k^r$ and $\eta^s = \delta_p^s$, (3) implies that

$$(x^r)_D - (x^r)_O = T_{kp}^r \Delta u \Delta v + o(\Delta u^2) + o(\Delta v^2). \tag{4}$$

Theorem. Let $A \in C^2$ be a tensor field in a neighbourhood of the point O. Then the following formula holds

$$(DA)_{j_1 \dots j_s}^{i_1 \dots i_r} = \lim_{\substack{\Delta u \rightarrow 0 \\ \Delta v \rightarrow 0}} \frac{1}{\Delta u \Delta v} \left[\phi_O^D (A_{j_1 \dots j_s}^{i_1 \dots i_r})_D - (A_{j_1 \dots j_s}^{i_1 \dots i_r})_O \right] \quad (5)$$

where ϕ_O^D denotes the parallel displacement along the curve $\tau_4^{-1} \tau_3^{-1} \tau_2^{-1} \tau_1^{-1}$, and $\xi^r = \delta_k^r$, $\eta^s = \delta_p^s$ (fig. 1).

Proof. It is well known that if a tensor A at any point of the manifold is transported parallelly round an infinitesimal circuit in the form of an infinitesimal parallelogram with adjacent edges dx^i and δx^i , then the principal part of the infinitesimal increment in $A_{j_1 \dots j_s}^{i_1 \dots i_r}$ is

$$\begin{aligned} \Delta A_{j_1 \dots j_s}^{i_1 \dots i_r} = & (-A_{j_1 \dots j_s}^{q \dots i_r} R_{qkp}^{i_1} - \dots - A_{j_1 \dots j_s}^{i_1 \dots q} R_{qkp}^{i_r} + \\ & + A_{q \dots j_s}^{i_1 \dots i_r} R_{j_1 kp}^q + \dots + A_{j_1 \dots q}^{i_1 \dots i_r} R_{j_s kp}^q) dx^k \delta x^p. \end{aligned} \quad (6)$$

Let us consider now the closed curve ODCBMO (fig. 1), where the points O and D are connected with a smooth curve $z(t)$. It can be considered as a small distortion of an infinitesimal parallelogram with adjacent edges $\eta^i = \delta_p^i$ and $\xi^i = \delta_k^i$. Let ϕ_D^O denotes the parallel displacement from O to D along the curve $z(t)$. The formula (6) can be applied and we obtain

$$\begin{aligned} \phi_D^O (\phi_O^D (A_{j_1 \dots j_s}^{i_1 \dots i_r})_D) - (A_{j_1 \dots j_s}^{i_1 \dots i_r})_D = \\ = - \left[(DA)_{j_1 \dots j_s}^{i_1 \dots i_r} + T_{kp}^q A_{j_1 \dots j_s}^{i_1 \dots i_r} ; q \right] \Delta u \Delta v + o(\Delta u^2) + o(\Delta v^2). \end{aligned}$$

Applying the formula for the parallel displacement of the tensor $\phi_O^D (A_{j_1 \dots j_s}^{i_1 \dots i_r})$ from O to D, and using that

$$(A_{j_1 \dots j_s}^{i_1 \dots i_r})_D = (A_{j_1 \dots j_s}^{i_1 \dots i_r})_O + \partial (A_{j_1 \dots j_s}^{i_1 \dots i_r}) / \partial x^k ((x^k)_D - (x^k)_O) + o(\Delta u^2) + o(\Delta v^2)$$

we obtain

$$\phi_O^D (A_{j_1 \dots j_s}^{i_1 \dots i_r})_D - (A_{j_1 \dots j_s}^{i_1 \dots i_r})_O = (DA)_{j_1 \dots j_s}^{i_1 \dots i_r} \Delta u \Delta v + o(\Delta u^2) + o(\Delta v^2).$$

If we divide this equality by $\Delta u \Delta v$ and put $\Delta u \rightarrow 0$, $\Delta v \rightarrow 0$ we will obtain the formula (5). ||

The above theorem gives the required geometrical interpretation of the antisymmetric differentiation D , using the parallel displacement of tensors. It is well known that the covariant differentiation can be written in the following form

$$A_{j_1 \dots j_s}^{i_1 \dots i_r}; k = \lim_{\Delta u \rightarrow 0} \frac{1}{\Delta u} \left[\phi_M^O(A_{j_1 \dots j_s}^{i_1 \dots i_r}) - (A_{j_1 \dots j_s}^{i_1 \dots i_r})_M \right],$$

where ϕ_M^O denotes the parallel displacement from O to M along the geodesic line $\tau_1(t)$ ($0 \leq t \leq \Delta u$) (fig. 1). We notice that both of these differentiations have similar geometrical interpretations.

Similar result can be obtained if one does not use indices. Indeed, if $A \in C^2$ is a tensor field in a neighbourhood of the point O and $X, Y \in T_O(M)$, then the following formula

$$D_{Y,X}(A) = \lim_{\substack{\Delta u \rightarrow 0 \\ \Delta v \rightarrow 0}} \frac{1}{\Delta u \Delta v} \left[\phi_O^D(A_D) - A_O \right] \quad (7)$$

holds, where

$$D_{Y,X} = \nabla_X \cdot \nabla_Y - \nabla_Y \cdot \nabla_X + \nabla(\nabla_Y X) - \nabla(\nabla_X Y).$$

We note that $\Delta u / \Delta v$ and $\Delta v / \Delta u$ in (5) and (7) are supposed to be bounded numbers.

R E F E R E N C E S

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ГЕОМЕТРИСКА ИНТЕРПРЕТАЦИЈА НА АНТИСИМЕТРИЧНОТО КОВАРИЈАНТНО ДИФЕРЕНЦИРАЊЕ

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Резиме

Во овој труд е дадена геометриска интерпретација на диференцирањето дефинирано со (1) односно (2), каде што A е тензорно поле од тип (r, s) . Всушност, се докажува равенството (5) каде што ϕ_O^D означува паралелно пренесување по должината на кривата $\tau_4^{-1} \tau_3^{-1} \tau_2^{-1} \tau_1^{-1}$, и $\xi^r = \delta_k^r$, $\eta^s = \delta_p^s$ (сл. 1).